# **Enclosures** PwrPak7-E1™



## COMPACT OEM7® ENCLOSURE DELIVERS NOVATEL'S LEADING SPAN® GNSS+INS TECHNOLOGY



## **SPAN: WORLD LEADING GNSS+INS TECHNOLOGY**

Synchronous Position, Attitude and Navigation (SPAN) technology brings together two different but complementary technologies: Global Navigation Satellite System (GNSS) positioning and inertial navigation. The absolute accuracy of GNSS positioning and the stability of Inertial Measurement Unit (IMU) gyro and accelerometer measurements are tightly coupled to provide an exceptional 3D navigation solution that is stable and continuously available, even through periods when satellite signals are blocked.

## **SPAN ENABLED MEMS RECEIVER**

The PwrPak7-E1 contains an Epson G320N MEMS IMU to deliver world class NovAtel SPAN technology in an integrated, single box solution. This product is commercially exportable and provides an excellent price/performance/size GNSS+INS solution.

## **FUTURE PROOFED SCALABILITY**

Capable of tracking all present and upcoming GNSS constellations and satellite signals, the PwrPak7-E1 is a robust, high precision receiver that is software upgradable in the field to provide the custom performance required for your application demands.

The PwrPak7-E1 has a powerful OEM7 GNSS engine, integrated MEMS IMU, built in Wi-Fi, on board NTRIP client and server support, and 16 GB of internal storage. It also has enhanced connection options including serial, USB, CAN and Ethernet.

## PRECISE THINKING MAKES IT POSSIBLE

Developed for efficient and rapid integration, our GNSS products have set the standard in quality and performance for over 20 years. State-of-the-art, lean manufacturing facilities in our North American headquarters produce the industry's most extensive line of OEM receivers, antennas and subsystems. All of our products are backed by a team of highly skilled design and customer support engineers, ready to answer your integration questions.

## **FEATURES**

- + SPAN enabled enclosure featuring NovAtel's tightly coupled GNSS+INS engine
- + 555 channel, all-constellation, multi-frequency positioning solution
- + Multi-channel L-Band supports
  TerraStar correction services
- + Commercially exportable IMU
- + Multiple communication interfaces for easy integration and installation
- + Built-in Wi-Fi support
- + 16 GB of internal storage
- Can be paired with an external receiver to support ALIGN® GNSS azimuth aiding for low dynamic applications

If you require more information about our enclosures, visit www.novatel.com/products/gnss-receivers/enclosures/



Contact NavtechGPS for product details. www.NavtechGPS.com +1-703-256-8900 • 800-628-0885 • info@navtechgps.com



# PwrPak7-E1™



#### PERFORMANCE1

#### **Channel Configuration**

555 Channels

L-Band

#### **Signal Tracking**

GPS L1 C/A, L1C, L2C, L2P, L5  $\mathsf{GLONASS}^2$ L1 C/A, L2C, L2P, L3, L5

E1, E5 AltBOC, E5a, Galileo<sup>3</sup>

E5b, E6

up to 5 channels

B1I, B1C, B2I, B2a, B3I BeiDou QZSS L1 C/A, L1C, L2C, L5, L6 NavIC (IRNSS) L1, L5 **SBAS** 

## **GNSS Horizontal Position** Accuracy (RMS)

1.5 m Single point L1 Single point L1/L2 1.2 m SBAS<sup>4</sup> 60 cm **DGPS** 40 cm TerraStar-L<sup>5</sup> 40 cm TerraStar-C PRO⁵ 2.5 cm 1 cm + 1 ppmInitialization time <10 s Initialization reliability >99.9%

#### **Maximum Data Rate**

GNSS Measurements up to 20 Hz **GNSS Position** up to 20 Hz INS Position/Attitude up to 200 Hz IMU Raw Data Rate 125 Hz

## Time to First Fix

Cold start<sup>6</sup> <39 s Hot start<sup>7</sup> <20 s 20 ns RMS Time Accuracy<sup>8</sup> Velocity Limit<sup>9</sup> 515 m/s

#### IMU PERFORMANCE<sup>10</sup>

#### **Gyroscope Performance**

Input range  $\pm 150 \text{ deg/s}$ Rate bias stability 3.5 deg/hr Angular random walk

0.1 deg/√hr

#### **Accelerometer Performance**

Range Bias stability 0.1 mg Velocity random walk

0.05 m/s/√hr

HS

#### **COMMUNICATION PORTS**

1 RS-232 up to 460,800 bps 2 RS-232/RS-422 selectable up to 460.800 bps HS

1 USB 2.0 (device) 1 USB 2.0 (host)

1 Ethernet 10/100 Mbps 1 CAN Bus 1 Mbps

1 Wi-Fi

3 Event inputs

3 Event outputs

1 Pulse Per Second output

1 Quadrature Wheel Sensor

#### PHYSICAL AND ELECTRICAL

**Dimensions** 147 x 125 x 55 mm Weight 510 q

Power

Input voltage +9 to +36 VDC Power consumption<sup>11</sup> 3.4 W

## Antenna LNA Power Output

Output voltage 5 VDC ±5% Maximum current 200 mA

#### Connectors

Antenna TNC USB device Micro A/B USB host Micro A/B Serial, CAN, Event I/O

DSUB HD26

RJ45 Ethernet Data Logging Push button Power SAL M12, 5 pin, male

#### Status LEDs

Power **GNSS** INS Data Logging

#### **ENVIRONMENTAL**

#### **Temperature**

Dust

-40°C to +75°C Operating -40°C to +85°C Storage **Humidity** 95% non-condensing

Waterproof IEC 60529 IPX7 IEC 60529 IP6X

## Vibration (operating)

Random MIL-STD-810G(CH1) Method 514.7 Category 24, 20g RMS Sinusoidal IEC 60068-2-6

## Acceleration (operating)

MIL-STD-810G(CH1), Method 513.7, Procedure II (16q)

## Bump (operating)

IEC 60068-2-27 (25 q)

#### Shock (operating)<sup>12</sup>

MIL-STD-810G(CH1), Method 516.7, Procedure 1, 40 q 11 ms terminal sawtooth

Compliance ISED, FCC, CE, RoHS, WEEE

## **INCLUDED ACCESSORIES**

- · Power cable
- USB cable
- · DSUB HD26 to DB9 RS-232 cable

## **OPTIONAL ACCESSORIES**

- · Full breakout cable for DSUB HD26 connector
- · DSUB HD26 to M12 IMU cable
- RJ45 Ethernet cable
- VEXXIS® GNSS-500 and GNSS-800 series antennas
- Compact GNSS antennas
- · GrafNav/GrafNet®
- · Inertial Explorer®
- · NovAtel Connect

For the most recent details of this product:

www.novatel.com/products/ gnss-receivers/enclosures/ pwrpak7-E1

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Version 5 Specifications subject to change without notice.

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Printed in Canada.

D21652 August 2019



## Navtech**GPS**

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## PERFORMANCE DURING GNSS OUTAGES<sup>1</sup>

Outage Duration	Positioning Mode	POSITION ACCURACY (M) RMS		VELOCITY ACCURACY (M/S) RMS		ATTITUDE ACCURACY (DEGREES) RMS		
		Horizontal	Vertical	Horizontal	Vertical	Roll	Pitch	Heading
0 s	RTK <sup>14</sup>	0.02	0.03	0.020	0.015	0.020	0.020	0.090
	SP	1.00	0.60	0.020	0.015	0.020	0.020	0.090
	PP <sup>15</sup>	0.01	0.02	0.015	0.010	0.008	0.008	0.038
10 s	RTK <sup>14</sup>	0.25	0.15	0.065	0.025	0.040	0.040	0.130
	SP	1.25	0.70	0.065	0.025	0.040	0.040	0.130
	PP <sup>15</sup>	0.01	0.02	0.015	0.010	0.008	0.008	0.038

- Typical values. Performance specifications subject to GNSS system characteristics, Signal-In-Space (SIS) operational degradation, ionospheric and tropospheric conditions, satellite geometry, baseline length, multipath effects and the presence of intentional or unintentional interference sources
- Hardware ready for L3 and L5.
- E1bc and E6bc support only.
- GPS only.

  Requires a subscription to a TerraStar data service. Subscriptions available from NovAtel.
- Typical value. No almanac or ephemerides and no approximate position or time.

  Typical value. Almanac and recent ephemerides saved and approximate position and time entered.

  Time accuracy does not include biases due to RF or antenna delay.

  Export licensing restricts operation to a maximum of 515 metres per second, message output impacted above 500 m/s.
- Supplied by IMU manufacturer.
   Typical value. Consult the OEM7 User Documentation for power supply considerations.
   GNSS only. IMU measurements may not be valid.

- 14. 1 ppm should be added to all position values to account for additional error due to baseline length. 15. Post-processing results using Inertial Explorer software. The survey data used to generate these statistics had frequent changes in azimuth.