SPAN® IMU-LN200



TACTICAL GRADE, LOW NOISE IMU COMBINES WITH NOVATEL'S GNSS TECHNOLOGY TO PROVIDE 3D POSITION, VELOCITY AND ATTITUDE SOLUTION



BENEFITS

SPAN: WORLD-LEADING GNSS+INS TECHNOLOGY

Synchronous Position, Attitude and Navigation (SPAN) technology brings together two different but complementary technologies: Global Navigation Satellite Systems (GNSS) positioning and inertial navigation. The absolute accuracy of GNSS positioning and the stability of Inertial Measurement Unit (IMU) gyro and accelerometer measurements are tightly coupled to provide an exceptional 3D navigation solution that is stable and continuously available, even through periods when satellite signals are blocked.

IMU-LN200 OVERVIEW

The IMU-LN200 is a tactical grade IMU containing closed-loop fiber optic gyros and solid-state silicon accelerometers. Low noise and stable accelerometer and gyro sensor biases make the IMU-LN200 an ideal choice for airborne mapping applications. IMU mounting is made easy by its small footprint.

The IMU-LN200 is available as a complete assembly, including the IMU and environmentally sealed enclosure. The LN200 is also available as a stand alone OEM product so integrators can easily pair it with a SPAN enabled receiver. The LN200 is ITAR controlled and requires export approval for customers outside the United States.

IMPROVE SPAN LN200 ACCURACY

Take advantage of NovAtel CORRECT™ to receive your choice of accuracy and performance, from decimetre to RTK-level positioning. For more demanding applications, Inertial Explorer® post-processing software from our Waypoint® Product Group can be used to post-process SPAN LN200 data and offers the highest level of accuracy with the system.

- + Low noise, low bias sensor excellent for airborne survey applications
- + Easy integration with NovAtel's SPAN capable GNSS+INS receivers
- + Streamlined enclosure and simple cabling

FEATURES

- + Closed-loop fiber optic gyro technology
- + 200 Hz data rate
- + 10-34 VDC power input
- + SPAN GNSS+INS functionality

If you require more information about our SPAN products, visit www.novatel.com/span



Contact NavtechGPS for product details. www.NavtechGPS.com +1-703-256-8900 • 800-628-0885 • info@navtechgps.com



IMU-LN200



SPAN SYSTEM PERFORMANCE¹

Horizontal Position Accuracy (RMS)

Single point L1/L2 12 m NovAtel CORRECT » SBAS² 60 cm » DGPS 40 cm » PPP^{3, 4} 40 cm TerraStar-L TerraStar-C 4 cm 1 cm + 1 ppm

Data Rate

200 Hz IMU measurements 200 Hz INS position INS velocity 200 Hz INS attitude 200 Hz

Time Accuracy⁵ 20 ns RMS

Max Velocity⁶ 515 m/s

IMU PERFORMANCE7

IMU-LN200

Gyro input range

±1000 deg/sec Gyro rate bias 1.0 deg/hr Gyro scale factor error

100 ppm

±15 g

Angular random walk

0.07 deg/√hr

Accelerometer input range8

±40 q

Accelerometer linearity

150 ppm Accelerometer scale factor error 300 ppm

Accelerometer bias 0.3 ma

IMU-LN200C

Gyro input range

±490 deg/sec 1.0 deg/hr Gyro rate bias Gyro scale factor error 100 ppm

Angular random walk

0.07 deg/√hr Accelerometer input range8

Accelerometer linearity

500 ppm

Accelerometer scale factor error 300 ppm

Accelerometer bias 1.0 mg

PHYSICAL AND ELECTRICAL

Dimensions

150 x 134 x 134 mm

Weight < 3.4 ka

Power

Power consumption

14 W (typical)

Input voltage +10 to +34 V

Connectors

Power SAL M12, 5 pin, male Data SAL M12, 4 pin, female Wheel sensor

SAL M12, 8 pin, male

ENVIRONMENTAL

Temperature

Operating -40°C to +55°C -40°C to +80°C Storage

Humidity MIL-STD-810G,

Method 507.5

Random Vibe MIL-STD-810G. Method 514.6 (2.0q)

MTBF 20.000 hrs

Environment IEC 60529 IP67

INCLUDED ACCESSORIES

- · Power cable
- Communication cable
- Wheel sensor cable

OPTIONAL ACCESSORIES

- · Mounting plate
- · Inertial Explorer postprocessing software

For the most recent details of this product:

www.novatel.com/products/ span-qnss-inertial-systems/ span-imus/imu-ln200tactical-grade-fiberoptic-gyros-fog-inertialmeasurement-unit-imu/

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Europe 44-1993-848-736

SE Asia and Australia 61-400-883-601

Version 1 Specifications subject to change without notice.

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PERFORMANCE DURING GNSS OUTAGES^{1,9}

Outage Duration	Positioning Mode	POSITION ACCURACY (M) RMS		VELOCITY ACCURACY (M/S) RMS		ATTITUDE ACCURACY (DEGREES) RMS		
		Horizontal	Vertical	Horizontal	Vertical	Roll	Pitch	Heading
0 s	RTK ¹⁰	0.02	0.03	0.010	0.010	0.010	0.010	0.020
	SP	1.00	0.60	0.010	0.010	0.010	0.010	0.020
	PP ¹¹	0.01	0.02	0.010	0.010	0.005	0.005	0.007
10 s	RTK ¹⁰	0.13	0.10	0.020	0.015	0.012	0.012	0.025
	SP	1.15	0.67	0.020	0.015	0.012	0.012	0.025
	PP ¹¹	0.01	0.02	0.020	0.010	0.005	0.005	0.007
60 s	RTK ¹⁰	2.75	0.85	0.100	0.025	0.017	0.017	0.040
	SP	3.50	1.40	0.100	0.025	0.017	0.017	0.040
	PP ¹¹	0.09	0.03	0.040	0.010	0.005	0.005	0.007

^{1.} Typical values. Performance specifications subject to GPS system characteristics. US DOD operational degradation, ionospheric and tropospheric conditions, satellite geometry, baseline length, multiplath effects and the presence of intentional or unintentional interference sources.

GPS-only.

Requires subscription to TerraStar data service. Subscriptions available from

TerraStar service available depends on the SPAN receiver used. See the receiver product sheet for details.

Time accuracy does not include biases due to RF or antenna delay. Export licensing restricts operation to a maximum of 515 metres/second.

Supplied by IMU manufacturer. GNSS receiver sustains tracking up to 4 g.

Steady state and outage performance remains the same for the C model. 10. 1 ppm should be added to all values to account for additional error due to baseline

length.
11. Post-processing results using Inertial Explorer software.