SPAN® SPAN-CPT™



SINGLE ENCLOSURE GNSS+INS RECEIVER DELIVERS 3D POSITION, VFI OCITY AND ATTITUDE



SPAN: WORLD LEADING GNSS+INS TECHNOLOGY

Synchronous Position, Attitude and Navigation (SPAN) technology brings together two different, but complementary technologies: Global Navigation Satellite System (GNSS) positioning and inertial navigation. The absolute accuracy of GNSS positioning and the stability of Inertial Measurement Unit (IMU) gyro and accelerometer measurements are tightly coupled to provide an exceptional 3D navigation solution that is stable and continuously available, even through periods when satellite signals are blocked.

SPAN-CPT OVERVIEW

SPAN-CPT is a compact, single enclosure GNSS+INS receiver, powered by NovAtel's world class OEM6® technology. Capable of delivering up to centimetre-level accuracy, customers can choose from a variety of positioning modes to ensure they have the optimal level of accuracy for their application.

The IMU components within the SPAN-CPT enclosure are comprised of Fiber Optic Gyros (FOG) and Micro Electromechanical System (MEMS) accelerometers, maximizing price/performance value. FOGs offer exceptionally long life and stable performance compared with other similar gyro technologies.

SPAN-CPT ADVANTAGES

The tight coupling of the GNSS and IMU measurements delivers the most satellite observations and the most accurate, continuous solution possible. Further, SPAN-CPT is comprised entirely of commercial components, which means cross-border difficulties involved with traditional GNSS+INS systems are greatly minimized.

IMPROVE SPAN-CPT ACCURACY

Take advantage of NovAtel CORRECT™ to receive your choice of accuracy and performance, from decimetre to RTK-level positioning. For more demanding applications Inertial Explorer® post processing software from our Waypoint® Products Group can be used to post-process SPAN data and offers the highest level of accuracy.

BENEFITS

- + Continuous, stable positioning
- + Easy to integrate into space constrained applications
- + Minimizes import/export issues
- + Withstands harsh environments
- + Innovative OEM6 technology

FEATURES

- + Fiber optic gyros and MEMS accelerometers
- + SBAS, NovAtel CORRECT™ with PPP and RTK support
- + 100 Hz raw data and solution
- Wheel sensor input for ground applications
- + Optional dual antenna

If you require more information about our SPAN products, visit www.novatel.com/span



SPAN-CPTTM

SPAN SYSTEM PERFORMANCE¹

Horizontal Position Accuracy (RMS)

Single point L1/L2 1.2 m NovAtel CORRECT™ » SBAS² 60 cm » DGPS 40 cm

» PPP³ 4 cm » RTK 1 cm + 1 ppm

Data Rate

GPS measurement 20 Hz
GPS position 20 Hz
IMU measurement 100 Hz
INS solution Up to 100 Hz
Time Accuracy⁴ 20 ns RMS
Max Velocity⁵ 515 m/s

IMU PERFORMANCE⁶

Gyroscope Performance

Gyro technology FOG
Output range ±375°/s
Bias 20°/hr
Bias stability ±1°/hr
Scale factor 1500 ppm
Angular random walk

0.0667°/√hr (max)

Accelerometer Performance

 Range
 ±10 g

 Bias
 50 mg

 Bias stability
 ±0.75 mg

 Scale factor
 4000 ppm

PHYSICAL AND ELECTRICAL

Dimensions

152 x 168 x 89 mm **Weight** 2.28 kg

Power

Power consumption 16 W max Input voltage +9 to +18 VDC

Antenna Port Power Output

Output voltage +5 VDC
Maximum current 100 mA

Connectors

z Power and I/O

MIL-DTL-38999 Series 3 Antenna Input TNC Female

COMMUNICATION PORTS

RS-232 UART COM	2
USB Device	1
CAN	1
Event Input Trigger	1
Configurable PPS	1

ENVIRONMENTAL

Temperature

Operating -40°C to +65°C Storage -50°C to +80°C **Humidity** 95% non-condensing

Waterproof

MIL-STD-810F, 506.4, Procedure I

INCLUDED ACCESSORIES

Combined I/O and power cable

OPTIONAL ACCESSORIES

- GPS-700 series antennas (dual-frequency required)
- ANT series antennas (dualfrequency required)
- RF cables-5, 10 and 30 m lengths
- Inertial Explorer postprocessing software

Optional Dual Antenna7

Baseline	Accuracy
0.5 m	0.4°
1.0 m	0.2°
2.0 m	0.1°

For the most recent details of this product:

www.novatel.com/products/ span-gnss-inertial-systems/ span-combined-systems/spancpt/

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Europe 44-1993-848-736

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Version 11 Specifications subject to change without notice.

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PERFORMANCE DURING GNSS OUTAGES¹

0.1	POSITION ACCURACY (M) RMS			VELOCITY ACCURACY (M/S) RMS		ATTITUDE ACCURACY (DEGREES) RMS		
Outage Duration	Positioning Mode	Horizontal	Vertical	Horizontal	Vertical	Roll	Pitch	Heading
0 s	RTK ⁸	0.02	0.03	0.015	0.010	0.020	0.020	0.060
	SP	1.00	0.60	0.020	0.010	0.020	0.020	0.060
	PP ⁹	0.01	0.02	0.015	0.010	0.008	0.008	0.035
10 s	RTK ⁸	0.25	0.18	0.045	0.025	0.030	0.030	0.080
	SP	1.20	0.75	0.050	0.025	0.030	0.030	0.080
	PP ⁹	0.02	0.02	0.015	0.010	0.008	0.008	0.035
60 s	RTK ⁸	6.10	2.05	0.255	0.080	0.045	0.045	0.100
	SP	7.00	2.60	0.260	0.080	0.045	0.045	0.100
	PP ⁹	0.23	0.11	0.020	0.012	0.013	0.013	0.038

Typical values. Performance specifications subject to GPS system characteristics, US DOD operational degradation, ionospheric and tropospheric conditions, satellite geometry, baseline length, multipath effects and the presence of intentional or unintentional interference.



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^{2.} GPS-only.

^{3.} Requires subscription to TerraStar data service. Subscriptions available from

^{4.} Time accuracy does not include biases due to RF or antenna delay.

^{5.} Export licensing restricts operation to a maximum of 515 metres/second.

^{6.} Supplied by IMU manufacturer

^{7.} Dual antenna requires a second NovAtel receiver to be paired with the SPAN-CPT.

^{8. 1} ppm should be added to all values to account for additional error due to baseline

^{9.} Post-processing accuracy using Inertial Explorer processing software.