



Inertial Measurement Unit / Attitude Heading Reference System

VectorNav VN-100 IMU/AHRS

Next Generation Embedded Navigation

PRODUCT OVERVIEW

The VN-100 is a miniature, light weight, low power, high-performance Inertial Measurement Unit (IMU) and Attitude and Heading Reference System (AHRS) available in a surface mount package or aluminum encased Rugged module. Incorporating the latest in MEMS technology, the VN-100 combines 3-axis accelerometers, gyros, magnetometers, a barometric pressure sensor and a 32-bit microprocessor into an extremely compact design.

The VN-100 computes and outputs a real-time, drift-free attitude solution (i.e. 3D orientation) that is continuous over a complete range of 360° motion. All VN-100 sensors go through a rigorous calibration process at the VectorNav production facility to ensure the highest quality inertial measurements and attitude estimates. The small size, high performance, and cost-effectiveness of the VN-100 provides unprecedented opportunities for embedded navigation.



HIGHLIGHTS

- > Attitude & Inertial Data at up to 1 kHz
- Continuous Attitude Solution Over Complete 360° Range of Motion
- Static Accuracy better than 0.5° in Pitch/Roll, 2° in Heading
- Individually Calibrated for Bias, Scale Factor, Misalignment, & Gyro G-Sensitivity
- Available with Full Temperature Compensation (-40°C to +85°C)
- Surface Mount Package (30-pin LGA)
 - Dimensions: 24 x 22 x 3 mm
 - Weight: 3 grams
- Rugged Package
 - Dimensions: 36 x 33 x 9 mm
 - Weight: 13 grams

FEATURES

- Vector Processing Engine (VPE) 1.0 Toolboxes
 - Real-Time Magnetic & Acceleration
 Disturbance Rejection
 - Adaptive Signal Filtering
 - Dynamic Filter Tuning
 - On-Board Hard & Soft Iron
 Compensation
- On-Board Gyro Drift Compensation
- Multi-Sensor Synchronization
- Inputs for External Magnetometers or Velocity Measurements (Airspeed, GPS)
- Optional Barometric Pressure Sensor

12-0002-NT-R1

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TECHNICAL SPECIFICATIONS

Attitude & Heading

Range (Heading/Roll):	±180 °
Range (Pitch):	±90 °
Static Accuracy (Heading):	2.0 °
Static Accuracy (Pitch/Roll):	0.5 °
Angular Resolution:	< 0.05 °
Repeatability:	< 0.2°
Output Rate:	200 Hz*

Gyro Specifications

Range:	±2000 °/s
In-Run Bias Stability:	< 10 °/hr
Linearity:	< 0.1 % FS
Noise Density:	0.005 °/s /√Hz
Bandwidth:	256 Hz
Alignment Error:	±0.05 °

Accelerometer Specifications

Range:	±16 g
Linearity:	< 0.5 % FS
Noise Density:	0.4 mg/ \sqrt{Hz}
Bandwidth:	260 Hz
Alignment Error:	±0.05 °

Magnetometer Specifications

±2.5 Gauss
< 0.1 %
140 µGauss/ \sqrt{Hz}
200 Hz
±0.05 °

Pressure Sensor Specifications**

10 to 1200 mbar
0.042 mbar
±1.5 mbar
±2.5 mbar
200 Hz

Environment

Operating Temp:-40°C to +85°CStorage Temp:-40°C to +85°C

Electrical

V to 5.5 V
V to 5.5 V
nA @ 3.3V
ómW
al TTL, SPI
al TTL, RS-232

Physical (Surface Mount Part)

Size:	24 x 22 x 3 mm
Weight:	3 g
Footprint:	30-pin LGA
Physical (Rugged)	
Size:	36 x 33 x 9 mm
Weight:	13 g
Connector:	Harwin M80-5001042

 \ast Rates of up to 1 kHz available upon request.

** Optional.

VN-100 DEVELOPMENT



- VN-100 Development Board
 - Pre-Soldered VN-100 Surface Mount Part with USB & RS-232 Interfaces
 - 30-Pin Header for Easy Prototyping



- VN-100 Rugged Development Kit
 - USB & Serial Adapter Cables
 - Connection Tool & Carrying Case

VN-100 DEVELOPMENT TOOLS

- Sensor Explorer GUI: Powerful and user-friendly GUI allows you to display sensor output as a 3D object, graph inertial data, configure sensor settings, perform data-logging, & more.
- Software Development Kit: Interface via C/C++, .NET & MATLAB development environments.
- Online Library: A large collection of inertial navigation knowledge and application notes is available on our website to help maximize VN-100 performance for your application.
- Engineering Support: Dedicated and responsive engineering support team with combined experience in sensing, guidance, navigation, and controls.
- Custom Solutions Available: Application-specific modeling & algorithm development; controls & closed-loop navigation solutions; custom form-factors & packaging; integration with other external sensors; displays, GUIs & other software packages; tailored calibrations; custom communication protocols.

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