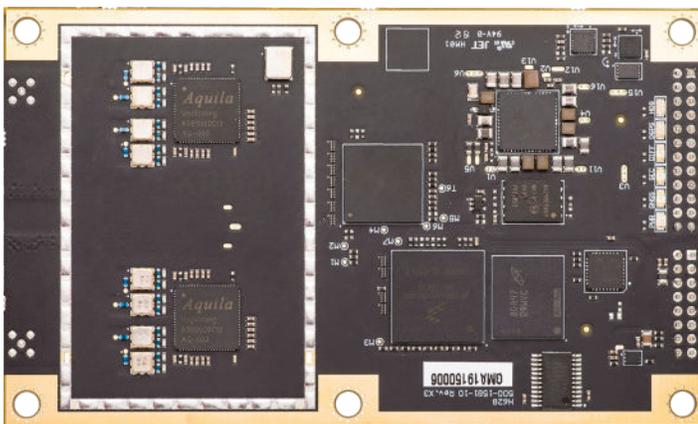




ADVANCED HEADING AND RTK POSITIONING



Develop sophisticated machine control and navigation solutions in a world full of complex dynamic environments. The Vega 40 is one of our most advanced GNSS heading and positioning boards.

The Vega 40 uses dual antenna ports to create a series of additional capabilities; including fast, high-accuracy heading over short baselines, RTK positioning, onboard Atlas L-band, RTK-enabled heave, low-power consumption, and precise timing.

Scalable Solutions

With the Vega 40, positioning is scalable and field upgradeable with all Hemisphere software and service options. Use the same centimeter-level accuracy in either single frequency mode, or employ the full performance and fast RTK initialization times over long distances with multi-frequency multi-constellation GNSS signals. High-accuracy L-band positioning from meter to sub-decimeter levels available via Atlas correction service.

Ease of Migration

Leverage the industry standard form factor for easy upgradeability from other manufacturers' modules.

Key Features

- Extremely accurate heading with long baselines
- Multi-frequency position, dual-frequency heading supporting GPS, GLONASS, BeiDou, Galileo, QZSS, IRNSS, and L-band
- Atlas® L-band capable to 4 cm RMS
- Athena™ GNSS engine providing best-in-class RTK performance
- Excellent coasting performance
- 5 cm RMS RTK-enabled heave accuracy
- Strong multipath mitigation and interference rejection
- New multi-axis gyro and tilt sensor for reliable coverage during short GNSS outages

GNSS Receiver Specifications

| | |
|--------------------------|---|
| Receiver Type: | Multi-Frequency GPS, GLONASS, BeiDou, Galileo, QZSS, IRNSS and Atlas |
| Signals Received: | GPS L1CA/L1P/L1C/L2P/L2C/L5 GLONASS G1/G2/G3, P1/P2 BeiDou B1i/B2i/B3i/B10C/B2A/B2B/ ACEBOC GALILEO E1BC/E5a/E5b/E6BC/ ALTB0C QZSS L1CA/L2C/L5/L1C/LEX IRNSS L5 Atlas |
| Channels: | 1,100+ |
| GPS Sensitivity: | -142 dBm |
| SBAS Tracking: | 3-channel, parallel tracking |
| Update Rate: | 10 Hz standard, 1 Hz or 20 Hz optional (with activation) |

Timing (1 PPS)

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|----------------------|--|
| Accuracy: | 20 ns |
| Rate of Turn: | 100°/s maximum |
| Cold Start: | 60 s typical (no almanac or RTC) |
| Warm Start: | 30 s typical (almanac and RTC) |
| Hot Start: | 10 s typical (almanac, RTC and position) |

Heading Fix: 10 s typical (Hot Start)

Antenna Input

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|--------------------------|----------------------|
| Impedance: | 50 Ω |
| Maximum Speed: | 1,850 kph (999 kts) |
| Maximum Altitude: | 18,288 m (60,000 ft) |

Accuracy

| Positioning: | RMS (67%) | 2DRMS (95%) |
|--|--------------------------------------|--------------------|
| Autonomous, no SA: ¹ | 1.2 m | 2.5 m |
| SBAS: ¹ | 0.3 m | 0.6 m |
| Atlas H10: ^{1,3} | 0.04 m | 0.08 m |
| Atlas H30: ^{1,3} | 0.15 m | 0.3 m |
| Atlas Basic: ^{1,3} | 0.50 m | 1.0 m |
| RTK: ¹ | 8 mm + 1 ppm | 15 mm + 2 ppm |
| Heading (RMS): | 0.16° rms @ 0.5 m antenna separation | |
| | 0.08° rms @ 1.0 m antenna separation | |
| | 0.04° rms @ 2.0 m antenna separation | |
| | 0.02° rms @ 5.0 m antenna separation | |
| Pitch/Roll (RMS): | 0.5° | |
| Heave (RMS): ¹ | 30 cm rms (DGNSS) , 5 cm rms (RTK) | |

L-Band Receiver Specifications

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|-----------------------------|----------------------|
| Receiver Type: | Single Channel |
| Channels: | 1525 to 1560 MHz |
| Sensitivity: | -130 dBm |
| Channel Spacing: | 5.0 kHz |
| Satellite Selection: | Manual and Automatic |
| Reacquisition Time: | 15 seconds (typical) |

1. Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity
2. Depends on multipath environment, number of satellites in view, SBAS coverage, satellite geometry, and ionospheric activity
3. Hemisphere GNSS proprietary
4. With future firmware upgrade and activation
5. CMR and CMR+ do not cover proprietary messages outside of the typical standard

Communications

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|---------------------------------|---|
| Ports: | 3 x full-duplex (1 x 3.3V CMOS, 1 x 3.3V CMOS with flow control, 1 x RS-232 with flow control) 1 x USB Host/Device 1 x Ethernet 10/100Mbps 2 x CAN (NMEA2000, ISO 11783) 1 x SPI |
| Interface Level: | 3.3V CMOS |
| Baud Rates: | 4800 - 115200 |
| Correction I/O Protocol: | Hemisphere GNSS proprietary ROX format, RTCM v2.3, RTCM v3.2, CMR ⁵ , CMR+ ⁵ |
| Data I/O Protocol: | NMEA 0183, Crescent binary |
| Timing Output: | 1 PPS, CMOS, active high, rising edge sync, 10 kΩ, 10 pF load |
| Event Marker Input: | CMOS, active low, falling edge sync, 10 kΩ, 10 pF load |

Power

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|--|------------------------------|
| Input Voltage: | 3.3 VDC +/- 5% |
| Power Consumption: | < 2.5 W all signals + L-band |
| Current Consumption: | 757 mA all signals + L-band |
| Antenna Voltage: | 5 VDC maximum |
| Antenna Short Circuit Protection: | Yes |
| Antenna Gain Input Range: | 10 to 40 dB |

Environmental

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|-------------------------------|---|
| Operating Temperature: | -40°C to +85°C (-40°F to +185°F) |
| Storage Temperature: | -40°C to +85°C (-40°F to +185°F) |
| Humidity: | 95% non-condensing (when in an enclosure) |

Mechanical Shock:

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|-------------------|---|
| Vibration: | EP455 Section 5.14.1 |
| EMC: | Operational (when mounted in an enclosure with screw mounting holes utilized) EP455 Section 5.15.1 Random CE (IEC 60945 Emissions and Immunity) FCC Part 15, Subpart B CISPR 22 |

Mechanical Dimensions:

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|----------------------------------|---|
| Dimensions: | 100 L x 60 W x 10 H (mm) 3.9 L x 2.4 W x 0.4 (in) |
| Weight: | 44 g (1.56 oz) |
| Status Indications (LED): | Power, Primary and Secondary GNSS lock, Differential lock, DGNS position, Heading |

Power/Data Connector:

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| Connector: | 24-pin male header 2 mm pitch 16-pin male header 2 mm pitch |
| Antenna Connectors: | MMCX, female, straight |

Aiding Devices

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|----------------------|---|
| Gyro: | Provides smooth and fast heading reacquisition. During loss of GNSS signals heading stability is degraded by < 1° per minute for up to 3 minutes. |
| Tilt Sensors: | Provide pitch, roll data and assist in fast start-up and reacquisition of heading solution |



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