



# GENERAL NAVIGATION HEADING AND POSITIONING COMPASS



Experience superior navigation from the accurate heading and positioning performance available with the Vector™ V200 GNSS compass. The multi-GNSS Vector V200 supports GPS, GLONASS, BeiDou, Galileo, and QZSS and offers an amazing world-wide 30 cm (RMS) accuracy via Hemisphere's Atlas GNSS global correction service.

The Vector V200 offers an incredible combination of simple installation, small form factor, and amazing performance. The compass - measuring only 35 cm in length - mounts easily to a flat surface or pole. The stability and maintenance-free design of the Vector V200 provides simple integration into autopilots, chart plotters, and AIS systems.

## Key Features

- L1 GPS, GLONASS, Galileo, BeiDou, QZSS
- 50 cm RMS world-wide positioning accuracy with Atlas corrections
- 0.75 degree heading accuracy in an amazingly small form factor
- Excellent in-band and out-of-band interference rejection
- Integrated gyro and tilt sensors help deliver fast start-up times and provide heading updates during temporary loss of satellites
- Provides heading, positioning, heave, roll, and pitch

## GNSS Sensor Specifications

<b>Receiver Type:</b>	Vector GNSS L1 Receiver
<b>Signals Received:</b>	GPS, GLONASS, BeiDou, Galileo, QZSS <sup>7</sup> , and Atlas
<b>Channels:</b>	424
<b>GPS Sensitivity:</b>	-142 dBm
<b>SBAS Tracking:</b>	2-channel, parallel tracking
<b>Update Rate:</b>	10 Hz standard, 20 Hz optional
<b>Timing (1 PPS)</b>	
<b>Accuracy:</b>	20 ns <sup>6</sup>
<b>Rate of Turn:</b>	100°/s maximum
<b>Compass Safe</b>	
<b>Distance:</b>	50 cm <sup>4</sup>
<b>Cold Start:</b>	60 s (no almanac or RTC)
<b>Warm Start:</b>	30 s typical (almanac and RTC)
<b>Hot Start:</b>	10 s typical (almanac, RTC and position)
<b>Heading Fix:</b>	10 s typical (valid position)
<b>Maximum Speed:</b>	1,850 kph (999 kts)
<b>Maximum Altitude:</b>	18,288 m (60,000 ft)
<b>Differential Options:</b>	SBAS, Atlas (L-band)

## Accuracy

<b>Positioning:</b>	<b>Default (RMS)</b>	<b>Optional (RMS)</b>
<b>Autonomous, no SA:</b> <sup>1</sup>	1.2 m	1.2 m
<b>SBAS:</b> <sup>2</sup>	0.3 m	0.3 m
<b>Atlas:</b> <sup>6</sup>	-	0.5 m
<b>Heading (RMS):</b>	1.5°	0.75°
<b>Pitch/Roll (RMS):</b>	1.5°	
<b>Heave (RMS):</b>	30 cm (DGPS) <sup>3</sup>	30 cm (Atlas) <sup>3,8</sup>

## L-Band Receiver Specifications

<b>Receiver Type:</b>	Single Channel
<b>Channels:</b>	1525 to 1560 MHz
<b>Sensitivity:</b>	-130 dBm
<b>Channel Spacing:</b>	5 kHz
<b>Satellite Selection:</b>	Manual or Automatic
<b>Reacquisition Time:</b>	15 sec (typical)

## Communications

<b>Ports:</b>	
<b>5-pin:</b>	NMEA2000
<b>12-pin:</b>	RS-232 (2 Tx, 2 Rx), RS-422 (1 Tx), 1 PPS or RS-422 (2 Tx, 1 Rx), 1 PPS
<b>Baud Rates:</b>	4800 - 115200
<b>Correction I/O</b>	
<b>Protocol:</b>	RTCM SC-104
<b>Data I/O Protocol:</b>	
<b>5-pin:</b>	NMEA 2000
<b>12-pin:</b>	NMEA 0183, Crescent binary <sup>5</sup>
<b>Timing Output:</b>	1 PPS (CMOS, rising edge sync <sup>6</sup> )

## Power

<b>Input Voltage:</b>	6 to 36 VDC
<b>Power Consumption:</b>	(multi-GNSS, typical continuous draw @ 12V)
<b>SBAS:</b>	3.2 W
<b>Atlas:</b>	3.6 W
<b>Power Isolation:</b>	Isolated to enclosure
<b>Reverse Polarity Protection:</b>	Yes

## Environmental

<b>Operating Temperature:</b>	-40°C to +70°C (-40°F to +158°F)
<b>Storage Temperature:</b>	-40°C to +85°C (-40°F to +185°F)
<b>Humidity:</b>	95% non-condensing
<b>Enclosure:</b>	ISO 60529:2013 for IPx6/IPx7/IPx9
<b>Vibration:</b>	IEC 60945:2002 Section 8.7 Vibration
<b>EMC:</b>	IEC60945:2002
	EN 301 489-1 V2.1.1
	EN 301 489-5 V2.1.1
	EN 301 489-19 V2.1.0
	EN 303 413 V1.1.1

## Mechanical

<b>Dimensions:</b>	
<b>No Mount:</b>	34.8 L x 15.8 W x 6.5 H (cm)
<b>LP Flat Mount:</b>	34.8 L x 15.8 W x 7.6 H (cm)
<b>HP Flat Mount:</b>	34.8 L x 15.8 W x 10.7 H (cm)
<b>Pole Mount:</b>	34.8 L x 15.8 W x 16.8 H (cm)
<b>Weight:</b>	
<b>Not including Mount:</b>	0.75 kg (1.7 lb)
<b>Including Mount:</b>	0.94 kg (2.1 lb)
<b>Power/Data Connector:</b>	5-pin or 12-pin

## Aiding Devices

<b>Gyro:</b>	Provides smooth heading, fast heading reacquisition and reliable 1° per minute heading for periods up to 3 minutes when loss of GPS has occurred
<b>Tilt Sensors:</b>	Provide pitch and roll data and assist in fast start-up and reacquisition of heading solution

1. Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity
2. Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry
3. Based on a 40 second time constant
4. This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation
5. Hemisphere GNSS proprietary
6. V200s only
7. With future firmware upgrade and activation
8. Requires optional Atlas subscription



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